

## 7.9 Nonhomogeneous Linear Systems.

Method: Decoupling through diagonalization

Suppose we are given  $\mathbf{v}' = A\mathbf{v} + \begin{bmatrix} g_1(t) \\ g_2(t) \\ \vdots \\ g_n(t) \end{bmatrix}$ , and

(\*) that  $A$  is diagonalizable. Suppose the eigenvalues are  $\lambda_1, \dots, \lambda_n$  and  $T = [\text{matrix of L.I. eigenvectors}]$ .

Then we know

$$D = \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{bmatrix} = T^{-1}AT,$$

Let  $\mathbf{u} = T^{-1}\mathbf{v}$  (change of variables).

Then  $\mathbf{v} = T\mathbf{u}$  and  $\mathbf{v}' = T\mathbf{u}'$ . Since  $A = TDT^{-1}$   
(\*) becomes

$$T\mathbf{u}' = (TDT^{-1})(T\mathbf{u}) + \mathbf{g}$$

these cancel

Multiply both sides by  $T^{-1}$ , to get

$$\mathbf{u}' = D\mathbf{u} + T^{-1}\mathbf{g}$$

Let  $\mathbf{h} = T^{-1}\mathbf{g}$ . Then  $\mathbf{u}' = D\mathbf{u} + \mathbf{h}$  is a decoupled

System:  $u'_i = \lambda_i u_i + h_i(t)$

⋮

$$u'_n = \lambda_n u_n + h_n(t)$$

Each can be solved as a linear first order eq as in Ch 2. Once this is done convert to the original variables, i.e.,  $\mathbf{v} = T\mathbf{u}$ .

Example 1  $V' = \begin{bmatrix} 4 & 3 \\ -6 & -5 \end{bmatrix} V + \begin{bmatrix} 2 \\ 3 \end{bmatrix}$ . Find general solution.

Find eigenvalues.  $\begin{vmatrix} 4-\lambda & 3 \\ -6 & -5-\lambda \end{vmatrix} = (\lambda-4)(\lambda+5) + 18$   
 $= \lambda^2 + \lambda - 20 + 18$   
 $= \lambda^2 + \lambda - 2 = (\lambda+2)(\lambda-1)$   
 $\Rightarrow \lambda = 1, -2.$

Find eigenvectors.

$$\boxed{\lambda=1}$$

$$\begin{bmatrix} 3 & 3 \\ -6 & -6 \end{bmatrix}$$

$$3a+3b=0$$

$$a=-b$$

$$\begin{bmatrix} -1 \\ 1 \end{bmatrix} \text{ eigenvector.}$$

$$\boxed{\lambda=-2}$$

$$\begin{bmatrix} 6 & 3 \\ -6 & -3 \end{bmatrix}$$

$$6a+3b=0$$

$$2a=-b$$

$$\begin{bmatrix} 1 \\ -2 \end{bmatrix} \text{ eigenvector.}$$

Diagonalize the system.

Let  $T = \begin{bmatrix} -1 & 1 \\ 1 & -2 \end{bmatrix}$ . Then  $T^{-1} = \begin{bmatrix} -2 & 1 \\ -1 & -1 \end{bmatrix}$ .

Check that  $D = T^{-1}AT = \begin{bmatrix} 1 & 0 \\ 0 & -2 \end{bmatrix}$ .

Let  $h = T^{-1}g = \begin{bmatrix} -2 & 1 \\ -1 & -1 \end{bmatrix} \begin{bmatrix} 2 \\ 3 \end{bmatrix} = \begin{bmatrix} -7 \\ -5 \end{bmatrix}$ .

Now system is decoupled  $\begin{bmatrix} u_1' \\ u_2' \end{bmatrix} = \begin{bmatrix} u_1 \\ -2u_2 \end{bmatrix} + \begin{bmatrix} -7 \\ -5 \end{bmatrix}$ .

Solve the Decoupled System

$$u_1' = u_1 - 7$$

$$\frac{du}{dt} = u - 7$$

$$\int \frac{du}{u-7} = \int dt$$

$$du/u-7 = t + C$$

$$|u-7| = e^{t+C} = e^C e^t$$

$$u-7 = \pm e^C e^t$$

$$u-7 = C e^t$$

$$u_1 = C_1 e^t + 7$$

$$u_2' = -2u_2 - 5$$

$$\frac{du}{dt} = -2u - 5$$

$$\int \frac{-2du}{-2u-5} = \int -2dt$$

$$|u|-2u-5| = -2t + C$$

$$-2u-5 = C e^{-2t}$$

$$-2u = C e^{-2t} + 5$$

$$u_2 = C_2 e^{-2t} - 5/2$$

Recover original ~~original~~ variables.

$$V = T U = \begin{bmatrix} -1 & 1 \\ 1 & -2 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} = \begin{bmatrix} -u_1 + u_2 \\ u_1 - 2u_2 \end{bmatrix}$$

$$= \begin{bmatrix} -C_1 e^t + 7 + C_2 e^{-2t} - 5/2 \\ C_1 e^t + 7 - 2C_2 e^{-2t} + 5 \end{bmatrix}$$

$$= C_1 \begin{bmatrix} -1 \\ 1 \end{bmatrix} e^t + C_2 \begin{bmatrix} 1 \\ -2 \end{bmatrix} e^{-2t} + \begin{bmatrix} -19/2 \\ 12 \end{bmatrix}$$

Done!

Example 2  $\mathbf{v}' = \begin{bmatrix} 2 & 2 \\ -6 & -5 \end{bmatrix} \mathbf{v} + \begin{bmatrix} 5\sin t \\ \cos t \end{bmatrix}$ . Find general solution.

Solution

Find eigenvalues

$$\begin{vmatrix} 2-\lambda & 2 \\ -6 & -5-\lambda \end{vmatrix} = (\lambda-2)(\lambda+5) + 12$$

$$= \lambda^2 + 3\lambda + 2$$

$$= (\lambda+1)(\lambda+2)$$

$$\lambda = -1, -2.$$

Find eigenvectors.

$$\lambda = -1$$

$$\begin{bmatrix} 3 & 2 \\ -6 & -4 \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$3a + 2b = 0 \quad \text{Use } \begin{bmatrix} -2 \\ 3 \end{bmatrix}.$$

$$\lambda = -2$$

$$\begin{bmatrix} 4 & 2 \\ -6 & -3 \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$4a + 2b = 0$$

$$2a + b = 0$$

$$\text{Use } \begin{bmatrix} 1 \\ -2 \end{bmatrix}$$

Find transformation matrix T and  $T^{-1}$ . Diagonalize.

$$T = \begin{bmatrix} -2 & 1 \\ 3 & -2 \end{bmatrix}, \quad T^{-1} = \begin{bmatrix} -2 & -1 \\ -3 & -2 \end{bmatrix}$$

$$\text{Check: } T^{-1} A T = \begin{bmatrix} -2 & -1 \\ -3 & -2 \end{bmatrix} \begin{bmatrix} 2 & 2 \\ -6 & -5 \end{bmatrix} \begin{bmatrix} -2 & 1 \\ 3 & -2 \end{bmatrix} = \begin{bmatrix} 2 & 1 \\ 6 & 4 \end{bmatrix} \begin{bmatrix} -2 & 1 \\ 3 & -2 \end{bmatrix} = \begin{bmatrix} -1 & 0 \\ 0 & -2 \end{bmatrix}$$

Decouple)

$$h = T^{-1} \begin{bmatrix} 5 \\ c \end{bmatrix} = \begin{bmatrix} -2 & -1 \\ -3 & -2 \end{bmatrix} \begin{bmatrix} 5 \\ c \end{bmatrix} = \begin{bmatrix} -25 - c \\ -35 - 2c \end{bmatrix}$$

$$\begin{bmatrix} u_1' \\ u_2' \end{bmatrix} = \begin{bmatrix} -u_1 \\ -2u_2 \end{bmatrix} + \begin{bmatrix} -25 - c \\ -35 - 2c \end{bmatrix}$$

$$u_1' = -u_1 - 25 - c$$

$$u_2' = -2u_2 - 35 - 2c$$

Solve the decoupled system.

$$u'_1 = -u_1 - 2s - c$$

$$u'_1 + u_1 = -2s - c.$$

Let  $u_h = Ce^{-t}$ . Let  $u_p = As + Bc$ .

Then  $u'_p = Ac - Bs$ .

$$u'_p + u_p = (A - B)s + (A + B)c$$

$$\text{must} = -2s - c.$$

$$\text{Thus, } A - B = -2$$

$$A + B = -1$$

$$2A = -3$$

$$A = -\frac{3}{2}$$

$$B = -1 - A = \frac{1}{2}$$

$$\text{Thus } u_1 = u_h + u_p = C e^{-t} - \frac{3}{2}s \cdot \omega t + \frac{1}{2}c \cos t$$

$$\text{Next } u'_2 = -2u_2 - 3s - 2c.$$

$$u'_1 + 2u_2 = -3s - 2c$$

Let  $u_h = C e^{-2t}$ . Let  $u_p = As + Bc$ .

Then  $u'_p = Ac - Bs$

$$u'_p + 2u_p = (2A - B)s + (2B + A)c$$

$$\text{must} = -3s - 2c.$$

$$\begin{cases} 2A - B = -3 \\ -2(A + 2B) = -2 \end{cases}$$

$$-5B = 1$$

$$B = -\frac{1}{5}$$

$$A = -2 - 2B = -2 + \frac{2}{5} = -\frac{8}{5}$$

$$u_p = -\frac{8}{5}s + -\frac{1}{5}c$$

$$u_2 = u_h + u_p = C_2 e^{-2t} - \frac{8}{5}s \cdot \omega t - \frac{1}{5}c \cos t$$

Finally, convert back to original variables.

$$V = Tu.$$

$$\begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} -2 & 1 \\ 3 & -2 \end{bmatrix} \begin{bmatrix} C_1 e^{-t} - \frac{3}{2} \sin t + \frac{1}{2} \cos t \\ C_2 e^{-2t} - \frac{8}{5} \sin t - \frac{1}{5} \cos t \end{bmatrix}$$

$$= \begin{bmatrix} -2C_1 e^{-t} + 3S - C + C_2 e^{-2t} - \frac{8}{5} S - \frac{1}{5} C \\ 3C_1 e^{-t} - \frac{9}{2} S + \frac{3}{2} C - 2C_2 e^{-2t} + \frac{16}{5} S + \frac{2}{5} C \end{bmatrix}$$

$$= C_1 \begin{bmatrix} -2 \\ 3 \end{bmatrix} e^{-t} + C_2 \begin{bmatrix} 1 \\ -2 \end{bmatrix} e^{-2t} + \begin{bmatrix} \frac{2}{5} S \sin t - \frac{6}{5} \cos t \\ -\frac{13}{10} S \sin t + \frac{19}{10} \cos t \end{bmatrix}$$

Check computer (Maple)

Done!

```
> dsolve({diff(x(t),t)=2*x(t)+2*y(t)+sin(t), diff(y(t),t)=-6*x(t)-5*y(t)+cos(t)}, [x(t),y(t)]);  
{x(t) =  $\frac{7}{5} \sin(t) - \frac{6}{5} \cos(t) + \frac{1}{2} e^{-2t} C1 - \frac{2}{3} e^{-t} C2$ , y(t) =  $\frac{19}{10} \cos(t) - \frac{13}{10} \sin(t) - e^{-2t} C1 + e^{-t} C2}$ }
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Looks different, but it is the same. Can you see that?

Example 3 with complex eigenvalues.

Let  $A = \begin{bmatrix} i & -1 \\ 1 & i \end{bmatrix}$  and  $g(t) = \begin{bmatrix} 2\sin wt \\ 2e^{2t} \end{bmatrix}$ .

Find the general solution to  $\mathbf{v}' = A\mathbf{v} + g$ .

Solution Show  $\lambda = (\pm i)$  are the eigenvalues.

Show  $\begin{bmatrix} 1 \\ -i \end{bmatrix}$  and  $\begin{bmatrix} 1 \\ i \end{bmatrix}$  are corresponding eigenvectors.

Decouple Let  $T = \begin{bmatrix} 1 & 1 \\ -i & i \end{bmatrix}$ . Then  $T^{-1} = \frac{1}{2i} \begin{bmatrix} i & -1 \\ i & i \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 & -i \\ 1 & i \end{bmatrix}$ .

Check  $T^{-1}AT = \begin{bmatrix} 1+i & 0 \\ 0 & 1-i \end{bmatrix}$ .

Let  $\mathbf{u} = T^{-1}\mathbf{v}$  be new variables. Then  $\mathbf{v} = Tu$  and  $\mathbf{v}' = Tu'$ .  
Hence

$$Tu' = ATu + g$$

$$\Rightarrow u' = T^{-1}ATu + T^{-1}g$$

$$\Rightarrow \begin{bmatrix} u'_1 \\ u'_2 \end{bmatrix} = \begin{bmatrix} 1+i & 0 \\ 0 & 1-i \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} + \begin{bmatrix} \sin t + ie^{2t} \\ \sin wt - ie^{2t} \end{bmatrix}$$

$$\Rightarrow \textcircled{1} \quad u'_1 = (1+i)u_1 + \sin t + ie^{2t}$$

$$\textcircled{2} \quad u'_2 = (1-i)u_2 + \sin wt - ie^{2t}$$

Solve ① for  $u_1(t)$ .

$$u_1' - (1+i)u_1 = \sin t + ie^{2t}.$$

$$u_h = C_1 e^{(1+i)t}. \quad \text{Let } u_p = A \sin t + B \cos t + D e^{2t}.$$

Then  $u_p' = A \cos t - B \sin t + 2D e^{2t}$

$$u_p' - (1+i)u_p = (-B - (1+i)A) \sin t + (A - (1+i)B) \cos t + (2D - (1+i)D) e^{2t}$$

$$\text{must } = \sin t + ie^{2t}.$$

$$\text{Thus, } -B - (1+i)A = 1$$

$$\text{and } A - (1+i)B = 0 \Rightarrow A = (1+i)B.$$

$$\Rightarrow -B - (1+i)(1+i)B = 1$$

$$-B(1 + (1+i)^2) = 1$$

$$B(1 + 1 + 2i - 1) = -1$$

$$B = \frac{-1}{1+2i} \cdot \frac{(1-2i)}{(1-2i)} = \frac{-1+2i}{5}$$

$$A = (1+i)B = \frac{(1+i)(-1+2i)}{5} = \frac{-3+i}{5}$$

$$\text{Next, } 2D - (1+i)D = i$$

$$D(2 - 1 - i) = i$$

$$D = \frac{i}{1-i} \cdot \frac{(1+i)}{(1+i)} = \frac{-1+i}{2}$$

$$\text{Thus, } u_1(t) = C_1 e^{(1+i)t} + \left(\frac{-3+i}{5}\right) \sin t + \left(\frac{-1+2i}{5}\right) \cos t + \left(\frac{-1+i}{2}\right) e^{2t}$$

Solve ② for  $u_2(t)$ , but we know that answer.

$$u_2(t) = C_2 e^{(1-i)t} + \left(\frac{-3-i}{5}\right) \sin t + \left(\frac{-1-2i}{5}\right) \cos t + \left(\frac{-1-i}{2}\right) e^{2t}.$$

Convert back to original variables

$$\begin{aligned} V = T u &= \begin{bmatrix} 1 & 1 \\ -i & i \end{bmatrix} \begin{bmatrix} C_1 e^{(1+i)t} + \left(\frac{-3+i}{5}\right) s + \left(\frac{-1+2i}{5}\right) c + \left(\frac{-1+i}{2}\right) e^{2t} \\ C_2 e^{(1-i)t} + \left(\frac{-3-i}{5}\right) s + \left(\frac{-1-2i}{5}\right) c + \left(\frac{-1-i}{2}\right) e^{2t} \end{bmatrix} \\ &= \begin{bmatrix} C_1 e^{(1+i)t} + C_2 e^{(1-i)t} - \frac{6}{5}s - \frac{2}{5}c - e^{2t} \\ -iC_1 e^{(1+i)t} + iC_2 e^{(1-i)t} + \frac{2}{5}s + \frac{4}{5}c + e^{2t} \end{bmatrix} \end{aligned}$$

Rewrite as real valued functions.

$$V_1 : C_1 e^{(1+i)t} + C_2 e^{(1-i)t} = (C_1 + C_2) \cos t e^t + i(C_1 - C_2) \sin t e^t$$

$$V_2 : -iC_1 e^{(1+i)t} + iC_2 e^{(1-i)t} = -i(C_1 - C_2) \cos t e^t + (C_1 + C_2) \sin t e^t.$$

Let  $P_1 = C_1 + C_2$  and  $P_2 = i(C_1 - C_2)$ .

Now

$$V_1 = P_1 \cos t e^t + P_2 \sin t e^t - \frac{6}{5} \sin t - \frac{2}{5} \cos t - e^{2t}$$

$$V_2 = -P_2 \cos t e^t + P_1 \sin t e^t + \frac{2}{5} \sin t + \frac{4}{5} \cos t + e^{2t}$$

Check with computer (Maple)

```
> dsolve({diff(x(t),t)=x(t)-y(t)+2*sin(t), diff(y(t),t)=x(t)+y(t)
+2*exp(2*t)}, [x(t),y(t)]);
{x(t) = e^t cos(t) - C2 - e^t sin(t) - C1 - 6/5 sin(t) - 2/5 cos(t) - e^2 t, y(t)
= e^t sin(t) - C2 + e^t cos(t) - C1 + 4/5 cos(t) + 2/5 sin(t) + e^2 t}
```

Example ④  $\vec{v}' = \begin{bmatrix} 8 & 4 \\ -9 & -4 \end{bmatrix} \vec{v} + \begin{bmatrix} \sin t \\ t \end{bmatrix}$ . Find general solution.  
with repeated eigenvalues.

Solution Find eigenvalues.

$$\begin{vmatrix} 8-\lambda & 4 \\ -9 & -4-\lambda \end{vmatrix} = (\lambda-8)(\lambda+4) + 36$$

$$= \lambda^2 - 4\lambda - 32 + 36$$

$$= \lambda^2 - 4\lambda + 4 = (\lambda-2)^2.$$

$$\lambda = 2, 2. \text{ Yikes!}$$

Find eigenvectors(5).

If there are two L.I. eigenvectors, we know what to do.  
If not .....

Let  $\lambda = 2$ .

$$\begin{bmatrix} 6 & 4 \\ -9 & -6 \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} 6 \\ 0 \end{bmatrix} \quad 6a + 4b = 0$$

$$3a + 2b = 0$$

Use  $\begin{bmatrix} -2 \\ 3 \end{bmatrix}$

No other L.I. e-vectors!

What to do? Find generalize eigenvector.

$$\begin{bmatrix} 6 & 4 \\ -9 & -6 \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} -2 \\ 3 \end{bmatrix}$$

$$6a + 4b = -2$$

$$-9a - 6b = 3 \quad \text{these are compatible.}$$

and redundant.

$$3a + 2b = -1$$

$$a = -\frac{2}{3}b - \frac{1}{3}$$

$$b = b$$

$$\begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} -2/3 \\ 1 \end{bmatrix} b + \begin{bmatrix} -1/3 \\ 0 \end{bmatrix}$$

Use any value for  $b$ . I let  $b=0$ .

Now  $\begin{bmatrix} -1/3 \\ 0 \end{bmatrix}$  is my generalized e.v.

Put  $\begin{bmatrix} 8 & 4 \\ -1 & -4 \end{bmatrix}$  into Jordan form.

Let  $T = [\text{eigenvector generalized e.v.}] = \begin{bmatrix} -2 & -\frac{1}{3} \\ 3 & 0 \end{bmatrix}$ .

Then  $T^{-1} = \begin{bmatrix} 0 & \frac{1}{3} \\ -3 & -2 \end{bmatrix}$ .

Check:  $T^{-1}AT = \begin{bmatrix} 0 & \frac{1}{3} \\ -3 & -2 \end{bmatrix} \begin{bmatrix} 8 & 4 \\ -9 & -4 \end{bmatrix} \begin{bmatrix} -2 & -\frac{1}{3} \\ 3 & 0 \end{bmatrix} = \begin{bmatrix} 2 & 1 \\ 0 & 2 \end{bmatrix} = J$ .

Next let  $h = T^{-1}g$  as before.

$$h = \begin{pmatrix} 0 & \frac{1}{3} \\ -3 & -2 \end{pmatrix} \begin{pmatrix} 5 \\ t \end{pmatrix} = \begin{pmatrix} t/3 \\ -35 - 2t \end{pmatrix}$$

Now we have, letting  $u = Tu^{-1}$ , that  $u' = Ju + h$ .

$$u'_1 = 2u_1 + u_2 + t/3$$

$$u'_2 = 2u_2 - 35 - 2t.$$

It is not completely decoupled. But  $u'_2$  is not dependent on  $u_1$ . So, we can solve for  $u_2$ .

Then we plug this into the  $u'$  equation, and solve it.

Solve for  $u_2$

$$u'_1 - 2u_1 = -3s - 2t.$$

$$u_1 = Ce^{2t} \quad \text{Let } u_p = As + Bc + Dt + E.$$

$$\text{Then } u'_p = Ac - Bs + D.$$

$$\text{Now } u'_p - 2u_p = (-2A - B)s + (A - 2B)c - 2Dt + D - 2E.$$

which must =  $-3s \quad -2t.$

$$-2A - B = -3$$

$$-2D = -2$$

$$A - 2B = 0$$

$$D - 2E = 0$$

$$-5B = -3$$

$$B = 1$$

$$B = 3/5$$

$$E = -\frac{1}{2}$$

$$A = 2B = 6/5.$$

$$\text{Thus } u_2 = C_2 e^{2t} + \frac{6}{5} \sin t + \frac{3}{5} \cos t + t + \frac{1}{2}.$$

Solve for  $u_1$

$$u'_1 = 2u_1 + u_2 + t/3$$

$$u'_1 - 2u_1 = C_2 e^{2t} + \frac{6}{5} \sin t + \frac{3}{5} \cos t + \frac{4}{3}t + \frac{1}{2}$$

$$\text{Let } u_1 = C_1 e^{2t}. \quad \text{Let } u_p = Pte^{2t} + As + Bc + Dt + E$$

$$\text{Plugging } u_p \text{ in: } u'_p = Pe^{2t} + 2Pte^{2t} + Ac - Bs + D$$

$$u'_p - 2u_p = Pe^{2t} + 2Pte^{2t} + (-2A - B)s + (A - 2B)c - 2Dt + D - 2E$$

$$\text{must = } C_2 e^{2t} + \frac{6}{5}s + \frac{3}{5}c + \frac{4}{3}t + \frac{1}{2}$$

Thus,  $P = C_2$ .

$$-2A - B = \frac{6}{5}$$

$$A - 2B = \frac{3}{5}$$

$$-5B = \frac{12}{5}$$

$$B = \frac{-12}{25}$$

$$A = \frac{3}{5} + 2B = \frac{15}{25} + \frac{-24}{25} = \frac{-9}{25}$$

$$-2D = \frac{4}{3} \Rightarrow D = -\frac{2}{3}$$

$$D - 2E = \frac{1}{2}$$

$$-\frac{2}{3} - 2E = \frac{1}{2}$$

$$-2E = \frac{1}{2} + \frac{2}{3} = \frac{7}{6}$$

$$\frac{3}{6} \quad \frac{4}{6}$$

$$E = -\frac{7}{12}$$

Thus,  $u_1 = C_1 e^{2t} + C_2 t e^{2t} - \frac{9}{25} \sin t + \frac{-12}{25} \cos t - \frac{2}{3}t - \frac{7}{12}$ .

Finally, convert back to the original variables  $\begin{bmatrix} v_1 \\ v_2 \end{bmatrix}$ .

Recall  $v = T^{-1} u$ . Thus,

$$\begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} -2 & \frac{1}{3} \\ 3 & 0 \end{bmatrix} \begin{bmatrix} C_1 e^{2t} + C_2 t e^{2t} - \frac{9}{25} s - \frac{12}{25} c - \frac{2}{3} t - \frac{7}{12} \\ C_2 e^{2t} + \frac{6}{5} s + \frac{3}{5} c + t + \frac{1}{2} \end{bmatrix}$$

$$\begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} \left(-2C_1 - \frac{C_2}{3}\right) e^{2t} - 2C_2 t e^{2t} + \left(\frac{18}{25} - \frac{2}{3}\right) s + \left(\frac{24}{25} + \frac{1}{5}\right) c + \left(\frac{4}{3} - \frac{1}{3}\right) t + \frac{14}{12} - \frac{1}{6} \\ 3C_1 e^{2t} + 3C_2 t e^{2t} - \frac{27}{25} s - \frac{36}{25} c - 2t - \frac{7}{4} \end{bmatrix}$$

$$= \begin{bmatrix} -2C_1 - \frac{C_2}{3} \\ 3C_1 \end{bmatrix} e^{2t} + \begin{bmatrix} -2C_2 \\ 3C_2 \end{bmatrix} t e^{2t} + \begin{bmatrix} \frac{8}{25} \\ -\frac{27}{25} \end{bmatrix} s \text{inh} + \begin{bmatrix} \frac{24}{25} \\ -\frac{36}{25} \end{bmatrix} c \text{ost} + \begin{bmatrix} 1 \\ -2 \end{bmatrix} t + \begin{bmatrix} 1 \\ -\frac{7}{4} \end{bmatrix}$$

This is the general solution.

Done!

Compare with computer (Maple)

```
> dsolve({diff(x(t),t)=8*x(t)+4*y(t)+sin(t), diff(y(t),t)=-9*x(t)
-4*y(t)+t}, [x(t),y(t)]);
{x(t) = -\frac{2}{3} e^{2t} - C2 - \frac{2}{3} e^{2t} t - C1 - \frac{1}{9} e^{2t} - C1 + \frac{8}{25} \sin(t) + \frac{19}{25} \cos(t) + 1 + t,
y(t) = e^{2t} - C2 + e^{2t} t - C1 - \frac{36}{25} \cos(t) - \frac{27}{25} \sin(t) - 2 t - \frac{7}{4}}
```

I made one mistake. Find it!